

# Introduction to multilevel algorithms

## I: Basic strategy

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## Current technical limitations in lattice QCD

- Rapidly growing autocorrelation times in the continuum limit
- Exponential loss of statistical precision at large distances
- ...

*The primary goal of the multilevel strategy to be discussed is to improve the precision of hadron propagator computations*

But there are further applications:

Wilson loops, glueball spectrum, generation of master fields, ...

**As a representative case, consider . . .**

Fields of classical spins  $\vec{s}(x)$  of unit length,  $\vec{s}(x)^2 = 1$ , on a 2d lattice

$$S(\vec{s}) = -\beta \sum_x \sum_{\mu} \vec{s}(x) \cdot \vec{s}(x + \hat{\mu})$$

$$\mathcal{Z} = \int \mathcal{D}[\vec{s}] e^{-S(\vec{s})}, \quad \langle \mathcal{O} \rangle = \frac{1}{\mathcal{Z}} \int \mathcal{D}[\vec{s}] \mathcal{O}(\vec{s}) e^{-S(\vec{s})}$$

Will focus on computing the 2-point function

$$G(x - y) = \langle \vec{s}(x) \cdot \vec{s}(y) \rangle$$

## Markov-chain MC

Generate a chain of fields

$$\vec{s}_1(x) \rightarrow \vec{s}_2(x) \rightarrow \vec{s}_3(x) \rightarrow \dots$$

according to some *transition probability density*  $T(\vec{s} \rightarrow \vec{s}')$

$$\int D[\vec{s}'] T(\vec{s} \rightarrow \vec{s}') = 1$$

$$\int D[\vec{s}] e^{-S(\vec{s})} T(\vec{s} \rightarrow \vec{s}') = e^{-S(\vec{s}')}$$

+ ergodicity requirements

$$\Rightarrow \bar{\mathcal{O}} = \frac{1}{N} \sum_{k=1}^N \mathcal{O}(\vec{s}_k) = \langle \mathcal{O} \rangle \pm \text{statistical error}$$

$$\text{statistical error} = \sqrt{\frac{2\tau(\mathcal{O})}{N}}\sigma(\mathcal{O})$$

$\tau(\mathcal{O})$  = integrated autocorrelation time of  $\mathcal{O}$

$\sigma(\mathcal{O})$  = standard deviation of  $\mathcal{O}$

- $\tau(\mathcal{O})$  depends on the simulation algorithm
- $\sigma(\mathcal{O})$  only on  $\mathcal{O}$

## Exponential loss of precision

In the case of  $\mathcal{O} = \vec{s}(x) \cdot \vec{s}(y)$  and at large  $|x - y|$

$$\langle \mathcal{O} \rangle \propto e^{-m|x-y|}$$

but

$$\frac{1}{2} \leq \tau(\mathcal{O}) \leq \tau_{\text{exp}} \quad (\text{a general property of Markov-chain MC})$$

$$\sigma(\mathcal{O}) = O(1) \quad (\text{explained later})$$

and thus

$$\text{relative statistical error} \propto \frac{e^{m|x-y|}}{\sqrt{N}}$$

## Ways to reduce the error

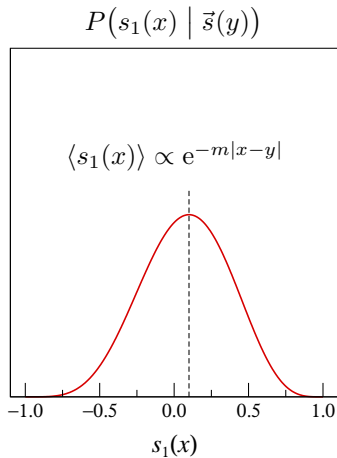
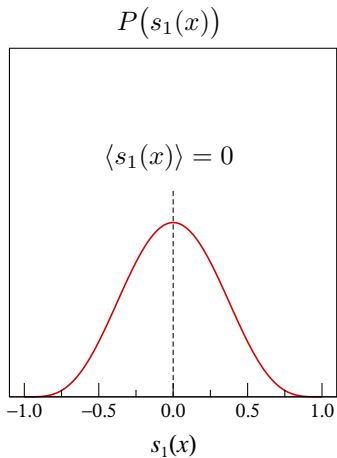
1. More powerful computers = wasteful, intellectual defeat!
2. Better simulation algorithms  $\Rightarrow$  smaller  $\tau(\mathcal{O})$ , but no exponential improvement
3. Construct observables  $\mathcal{O}'$  such that

$$\langle \mathcal{O}' \rangle = \langle \mathcal{O} \rangle \quad \text{and} \quad \sigma(\mathcal{O}') \ll \sigma(\mathcal{O})$$

Improvement can be exponential!

*The multilevel strategy is to construct improved observables by exploiting the locality of the theory*

Why is  $\sigma(\mathcal{O}) = O(1)$ ?



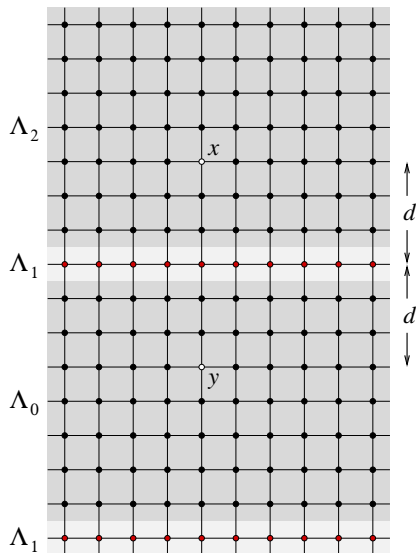


## Local sampling

Consider a  $T \times L$  lattice with periodic boundary conditions

At fixed spins on  $\Lambda_1$ :

- $\Lambda_0$  and  $\Lambda_2$  are decoupled
- Spin fields on  $\Lambda_0, \Lambda_2$  may be sampled independently
- E.g. through a HMC algorithm



## 2-level algorithm

**Level 0:**  $n_0$  global updates

**Level 1:**  $n_1$  local updates at fixed spins on  $\Lambda_1$

$$\underbrace{\vec{s}_1 \rightarrow \vec{s}_2 \rightarrow \dots \rightarrow \vec{s}_{n_0}}_{\text{global}} \rightarrow \underbrace{\vec{s}_{n_0+1} \rightarrow \vec{s}_{n_0+2} \rightarrow \dots \rightarrow \vec{s}_{n_0+n_1}}_{\text{local}} \rightarrow \dots$$

- Perform  $N$  such update cycles
- For all cycles  $k = 1, \dots, N$  compute

$$[\vec{s}(x)]_k = \frac{1}{n_1} \sum_{j=1}^{n_1} \vec{s}_{k(n_0+n_1)+j}(x) \quad \text{and} \quad [\vec{s}(y)]_k = \dots$$

$$\Rightarrow \langle \vec{s}(x) \cdot \vec{s}(y) \rangle = \frac{1}{N} \sum_{k=1}^N [\vec{s}(x)]_k \cdot [\vec{s}(y)]_k \pm \text{statistical error}$$

## Is this a correct algorithm?

**Lemma:** If  $T_1(\vec{s} \rightarrow \vec{s}')$  and  $T_2(\vec{s} \rightarrow \vec{s}')$  are valid transition probabilities, so is

$$(T_1 T_2)(\vec{s} \rightarrow \vec{s}') = \int D[\vec{r}] T_1(\vec{s} \rightarrow \vec{r}) T_2(\vec{r} \rightarrow \vec{s}')$$

In particular,  $T_1 T_2$  preserves the equilibrium distribution  $e^{-S(\vec{s})}$ .

⇒ The spins

$$\vec{s}_{k(n_0+n_1)+i}(x) \quad \text{and} \quad \vec{s}_{k(n_0+n_1)+j}(y)$$

have the correct joint distribution, for all  $i, j$ , and

$$[\vec{s}(x)]_k \cdot [\vec{s}(y)]_k = \frac{1}{n_1^2} \sum_{i,j=1}^{n_1} \vec{s}_{k(n_0+n_1)+i}(x) \cdot \vec{s}_{k(n_0+n_1)+j}(y)$$

is therefore a correct stochastic estimator of the 2-point function

## Choice of $n_0$ and $n_1$

1. Choose  $n_1$  such that

$$\sigma([s_1(x)]) \sim \langle [s_1(x)] \rangle$$

at fixed  $\vec{s}(z)$  on  $\partial\Lambda$

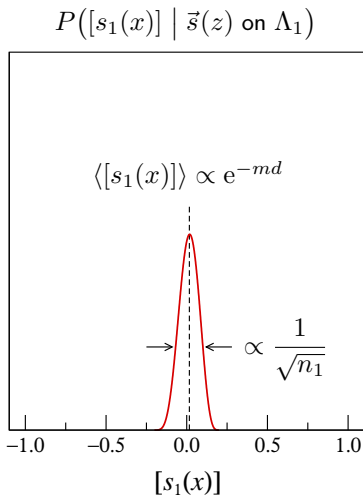
2. Since

$$[\vec{s}(x)] \cdot [\vec{s}(y)] \sim e^{-2md} = e^{-m|x-y|}$$

the statistical error is then of order

$$\sqrt{\frac{2\tau}{N}} e^{-m|x-y|}$$

3. Increase  $n_0$  until  $\tau \simeq \frac{1}{2}$



## Scaling behaviour

The number of updates is  $N (n_0 + n_1)$ , but only

$$n_1 \propto e^{2md} = e^{m|x-y|}$$

scales exponentially with  $|x - y|$

**With respect to the 1-level algorithm, where  $N \propto e^{2m|x-y|}$ ,  
an exponential improvement is thus achieved!**

Essentially a consequence of the representation

$$\langle \vec{s}(x) \cdot \vec{s}(y) \rangle = \langle [\vec{s}(x)] \cdot [\vec{s}(y)] \rangle$$

through exponentially small factors that can be computed independently

**If you have some spare time . . .**

Design a 3-level algorithm with an even better scaling behaviour!